

Topological indices of Join graph of zero divisor graphs of direct product of three finite fields

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Abstract

In this paper, we calculate the Wiener index, some degree-based topological indices, and some eccentricity-based topological indices of Join graph of $\Gamma(F_1 \times F_2 \times F_3)$ and $\Gamma(J_1 \times J_2 \times J_3)$, where $F_1, F_2, F_3, J_1, J_2, J_3$ are finite fields of order at least two. The vertex set of $\Gamma(F_1 \times F_2 \times F_3)$ ($\Gamma(J_1 \times J_2 \times J_3)$) is $Z^*(F_1 \times F_2 \times F_3)$ ($Z^*(J_1 \times J_2 \times J_3)$), the set of non-zero zero divisors, and two distinct vertices $(x_1, x_2, x_3), (y_1, y_2, y_3)$ are adjacent if and only if $(x_1, x_2, x_3) \cdot (y_1, y_2, y_3) = (0, 0, 0)$, the additive identity of the ring $F_1 \times F_2 \times F_3$ ($J_1 \times J_2 \times J_3$). The vertex set of Join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is $V(\Gamma(F_1 \times F_2 \times F_3)) \cup V(\Gamma(J_1 \times J_2 \times J_3))$ and edge set is $E(\Gamma(F_1 \times F_2 \times F_3)) \cup E(\Gamma(J_1 \times J_2 \times J_3)) \cup \{(x_1, x_2, x_3) \cdot (y_1, y_2, y_3) : (x_1, x_2, x_3) \in V(\Gamma(F_1 \times F_2 \times F_3)), (y_1, y_2, y_3) \in V(\Gamma(J_1 \times J_2 \times J_3))\}$.

Key words: Zero divisor graph, Join graph, Wiener index, degree based topological indices, eccentricity based topological indices.

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1 Introduction

Consider the rings $F_1 \times F_2 \times F_3$ and $J_1 \times J_2 \times J_3$, where $F_1, F_2, F_3, J_1, J_2, J_3$ are finite fields of order at least two. In this paper we consider the zero divisor graph defined by Anderson and Livingston [2] for the rings $F_1 \times F_2 \times F_3$ and $J_1 \times J_2 \times J_3$, denoted by $\Gamma(F_1 \times F_2 \times F_3)$ and $\Gamma(J_1 \times J_2 \times J_3)$. The vertex set of $\Gamma(F_1 \times F_2 \times F_3)$ ($\Gamma(J_1 \times J_2 \times J_3)$) is $Z^*(F_1 \times F_2 \times F_3)$ ($Z^*(J_1 \times J_2 \times J_3)$) where two distinct non-zero zero divisors $(x_1, x_2, x_3), (y_1, y_2, y_3)$ are adjacent if and only if $(x_1, x_2, x_3) \cdot (y_1, y_2, y_3) = (0, 0, 0)$, the additive identity of the ring $F_1 \times F_2 \times F_3$ ($J_1 \times J_2 \times J_3$). The Join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is the graph with vertex set $V(\Gamma(F_1 \times F_2 \times F_3)) \cup V(\Gamma(J_1 \times J_2 \times J_3))$ and edge set is $E(\Gamma(F_1 \times F_2 \times F_3)) \cup E(\Gamma(J_1 \times J_2 \times J_3)) \cup \{(x_1, x_2, x_3) \cdot (y_1, y_2, y_3) : (x_1, x_2, x_3) \in V(\Gamma(F_1 \times F_2 \times F_3)), (y_1, y_2, y_3) \in V(\Gamma(J_1 \times J_2 \times J_3))\}$. [12]

For more information on graphs defined on rings which are products of finite fields, we refer to [6, 7, 8, 9]. For basic concepts of graph theory, we refer to [17] and for ring theory we refer to [10].

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2 Wiener index and some degree based topological indices

In this section, we calculate the Wiener index, some degree based topological indices such as [16] Sombor index, [15] the first and second Zagreb indices, forgotten topological index, the Narumi-Katayama index, the first and second multiplicative Zagreb indices, atom-bond-connectivity index of the Join graph of $\Gamma(F_1 \times F_2 \times F_3)$ and $\Gamma(J_1 \times J_2 \times J_3)$.

Example 2.1. [9] Let $V(\Gamma(F_1 \times F_2 \times F_3)) = \cup_{i=1}^6 A_i$, where

$$A_1 = \{(0, a_2, a_3) : a_2 \in F_2 \setminus \{0\}, a_3 \in F_3 \setminus \{0\}\}.$$

$$A_2 = \{(a_1, 0, a_3) : a_1 \in F_1 \setminus \{0\}, a_3 \in F_3 \setminus \{0\}\}.$$

$$A_3 = \{(a_1, a_2, 0) : a_1 \in F_1 \setminus \{0\}, a_2 \in F_2 \setminus \{0\}\}.$$

$$A_4 = \{(0, 0, a_3) : a_3 \in F_3 \setminus \{0\}\}.$$

$$A_5 = \{(0, a_2, 0) : a_2 \in F_2 \setminus \{0\}\}.$$

$$A_6 = \{(a_1, 0, 0) : a_1 \in F_1 \setminus \{0\}\}.$$

$$\text{We have, } |A_1| = (|F_2| - 1)(|F_3| - 1), |A_2| = (|F_1| - 1)(|F_3| - 1),$$

$$|A_3| = (|F_1| - 1)(|F_2| - 1), |A_4| = |F_3| - 1, |A_5| = |F_2| - 1, |A_6| = |F_1| - 1.$$

[9] Let $V(\Gamma(J_1 \times J_2 \times J_3)) = \cup_{i=1}^6 B_i$, where

$$B_1 = \{(0, b_2, b_3) : b_2 \in J_2 \setminus \{0\}, b_3 \in J_3 \setminus \{0\}\}.$$

$$B_2 = \{(b_1, 0, b_3) : b_1 \in J_1 \setminus \{0\}, b_3 \in J_3 \setminus \{0\}\}.$$

$$B_3 = \{(b_1, b_2, 0) : b_1 \in J_1 \setminus \{0\}, b_2 \in J_2 \setminus \{0\}\}.$$

$$B_4 = \{(0, 0, b_3) : b_3 \in J_3 \setminus \{0\}\}.$$

$$B_5 = \{(0, b_2, 0) : b_2 \in J_2 \setminus \{0\}\}.$$

$$B_6 = \{(b_1, 0, 0) : b_1 \in J_1 \setminus \{0\}\}.$$

$$\text{We have, } |B_1| = (|J_2| - 1)(|J_3| - 1), |B_2| = (|J_1| - 1)(|J_3| - 1),$$

$$|B_3| = (|J_1| - 1)(|J_2| - 1), |B_4| = |J_3| - 1, |B_5| = |J_2| - 1, |B_6| = |J_1| - 1.$$

Now we consider the Join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ with vertex set

$$V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = V(\Gamma(F_1 \times F_2 \times F_3)) \cup V(\Gamma(J_1 \times J_2 \times J_3))$$

and edge set $E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) =$

$$E(\Gamma(F_1 \times F_2 \times F_3)) \cup E(\Gamma(J_1 \times J_2 \times J_3)) \cup \{(x_1, x_2, x_3) \cdot (y_1, y_2, y_3) : (x_1, x_2, x_3) \in V(\Gamma(F_1 \times F_2 \times F_3)), (y_1, y_2, y_3) \in V(\Gamma(J_1 \times J_2 \times J_3))\}. [12]$$

The degree of each vertex in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ can be determined as



$$d_x = \begin{cases} |F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_1 \\ |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_2 \\ |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_3 \\ |F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_4 \\ |F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_5 \\ |F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))| & x \in A_6. \\ |J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_1 \\ |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_2 \\ |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_3 \\ |J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_4 \\ |J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_5 \\ |J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))| & x \in B_6. \end{cases}$$

The edge set $E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$ is given below :

$xy \in E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$ if

$$\left\{ \begin{array}{ll} x \in A_1, y \in A_6 & \text{and number of such edges is } (|F_2| - 1)(|F_3| - 1)(|F_1| - 1) \\ x \in A_2, y \in A_5 & \text{and number of such edges is } (|F_1| - 1)(|F_3| - 1)(|F_2| - 1) \\ x \in A_3, y \in A_4 & \text{and number of such edges is } (|F_1| - 1)(|F_2| - 1)(|F_3| - 1) \\ x \in A_4, y \in A_5 & \text{and number of such edges is } (|F_1| \cdot |F_2| - 1)(|F_1| \cdot |F_3| - 1) \\ x \in A_4, y \in A_6 & \text{and number of such edges is } (|F_1| \cdot |F_2| - 1)(|F_2| \cdot |F_3| - 1) \\ x \in A_5, y \in A_6 & \text{and number of such edges is } (|F_1| \cdot |F_3| - 1)(|F_2| \cdot |F_3| - 1). \\ x \in B_1, y \in B_6 & \text{and number of such edges is } (|J_2| - 1)(|J_3| - 1)(|J_1| - 1) \\ x \in B_2, y \in B_5 & \text{and number of such edges is } (|J_1| - 1)(|J_3| - 1)(|J_2| - 1) \\ x \in B_3, y \in B_4 & \text{and number of such edges is } (|J_1| - 1)(|J_2| - 1)(|J_3| - 1) \\ x \in B_4, y \in B_5 & \text{and number of such edges is } (|J_1| \cdot |J_2| - 1)(|J_1| \cdot |J_3| - 1) \\ x \in B_4, y \in B_6 & \text{and number of such edges is } (|J_1| \cdot |J_2| - 1)(|J_2| \cdot |J_3| - 1) \\ x \in B_5, y \in B_6 & \text{and number of such edges is } (|J_1| \cdot |J_3| - 1)(|J_2| \cdot |J_3| - 1). \end{array} \right.$$

$x \in V(\Gamma(F_1 \times F_2 \times F_3)), y \in V(\Gamma(J_1 \times J_2 \times J_3))$ and number of such edges is $|V(\Gamma(F_1 \times F_2 \times F_3))| \cdot |V(\Gamma(J_1 \times J_2 \times J_3))|$.

1. The Wiener index of join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is

$$\begin{aligned} & W(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) \\ &= |E(\Gamma(F_1 \times F_2 \times F_3))| + |E(\Gamma(J_1 \times J_2 \times J_3))| \\ &+ |V(\Gamma(F_1 \times F_2 \times F_3))| \cdot |V(\Gamma(J_1 \times J_2 \times J_3))| \\ &+ \left[\left(|V(\Gamma(F_1 \times F_2 \times F_3))|, 2 \right) - |E(\Gamma(F_1 \times F_2 \times F_3))| \right] \\ &+ \left[C \left(|V(\Gamma(J_1 \times J_2 \times J_3))|, 2 \right) - |E(\Gamma(J_1 \times J_2 \times J_3))| \right]. \end{aligned}$$

Proof. According to [9, Example 3.1],

$\text{diam}(\Gamma(F_1 \times F_2 \times F_3)) = 3$, $\text{diam}(\Gamma(J_1 \times J_2 \times J_3)) = 3$. Let $x, y \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$. If both $x, y \in V(\Gamma(F_1 \times F_2 \times F_3))$ and $xy \notin E(\Gamma(F_1 \times F_2 \times F_3))$, then, since both x, y are adjacent to each and every vertex of $V(\Gamma(J_1 \times J_2 \times J_3))$ in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$, it follows that $d(x, y) = 2$. Similarly, if both $x, y \in V(\Gamma(J_1 \times J_2 \times J_3))$ and $xy \notin E(\Gamma(J_1 \times J_2 \times J_3))$, then, $d(x, y) = 2$ in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$.

If $x \in V(\Gamma(F_1 \times F_2 \times F_3))$, $y \in V(\Gamma(J_1 \times J_2 \times J_3))$, in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$, then, clearly, $d(x, y) = 1$. Therefore, the diameter of the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is 2. We determine the number of pairs of vertices which are at distance 1 and 2 in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$. The number of pairs of vertices which are at distance 1 in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is $E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$ which is

$$\begin{aligned} & 3 \left[(|F_1| - 1)(|F_2| - 1)(|F_3| - 1) \right] + \left[(|F_1| \cdot |F_2| - 1) + (|F_1| \cdot |F_3| - 1) + (|F_2| \cdot |F_3| - 1) \right] \\ & + 3 \left[(|J_1| - 1)(|J_2| - 1)(|J_3| - 1) \right] + \left[(|J_1| \cdot |J_2| - 1) + (|J_1| \cdot |J_3| - 1) + (|J_2| \cdot |J_3| - 1) \right] \\ & + |V(\Gamma(F_1 \times F_2 \times F_3))| \cdot |V(\Gamma(J_1 \times J_2 \times J_3))| = |E(\Gamma(F_1 \times F_2 \times F_3))| + \\ & |E(\Gamma(J_1 \times J_2 \times J_3))| + |V(\Gamma(F_1 \times F_2 \times F_3))| \cdot |V(\Gamma(J_1 \times J_2 \times J_3))|. \end{aligned}$$

Now we compute the number of pairs of vertices which are at distance 2 in the join graph $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$. The number of pairs of vertices which are at distance 2, with $x, y \in V(\Gamma(F_1 \times F_2 \times F_3))$, $xy \notin E(\Gamma(F_1 \times F_2 \times F_3))$ is

$$\begin{aligned} & C(|V(\Gamma(F_1 \times F_2 \times F_3))|, 2) - 3 \left[(|F_1| - 1)(|F_2| - 1)(|F_3| - 1) \right] + \left[(|F_1| \cdot |F_2| - 1) \right. \\ & \quad \left. + (|F_1| \cdot |F_3| - 1) + (|F_2| \cdot |F_3| - 1) \right] \\ & = C(|V(\Gamma(F_1 \times F_2 \times F_3))|, 2) - |E(\Gamma(F_1 \times F_2 \times F_3))|. \end{aligned}$$

Similarly, number of pairs of vertices which are at distance 2, with $x, y \in V(\Gamma(J_1 \times J_2 \times J_3))$, $xy \notin E(\Gamma(J_1 \times J_2 \times J_3))$ is

$$\begin{aligned} & C(|V(\Gamma(J_1 \times J_2 \times J_3))|, 2) - 3 \left[(|J_1| - 1)(|J_2| - 1)(|J_3| - 1) \right] + \left[(|J_1| \cdot |J_2| - 1) \right. \\ & \quad \left. + (|J_1| \cdot |J_3| - 1) + (|J_2| \cdot |J_3| - 1) \right] \\ & = C(|V(\Gamma(J_1 \times J_2 \times J_3))|, 2) - |E(\Gamma(J_1 \times J_2 \times J_3))|. \end{aligned}$$

Therefore, the Wiener index is $W(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$
 $= |E(\Gamma(F_1 \times F_2 \times F_3))| + |E(\Gamma(J_1 \times J_2 \times J_3))|$
 $+ |V(\Gamma(F_1 \times F_2 \times F_3))| \cdot |V(\Gamma(J_1 \times J_2 \times J_3))|$

$$+ \left[C(|V(\Gamma(F_1 \times F_2 \times F_3))|, 2) - |E(\Gamma(F_1 \times F_2 \times F_3))| \right] \\ + \left[C(|V(\Gamma(J_1 \times J_2 \times J_3))|, 2) - |E(\Gamma(J_1 \times J_2 \times J_3))| \right]. \quad \square$$

2. The first Zagreb index [11, 14] is $M_1(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$

$$= \sum_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} (deg(x))^2 \\ = \sum_{x \in A_1} (deg(x))^2 + \sum_{x \in A_2} (deg(x))^2 + \sum_{x \in A_3} (deg(x))^2 + \sum_{x \in A_4} (deg(x))^2 \\ + \sum_{x \in A_5} (deg(x))^2 + \sum_{x \in A_6} (deg(x))^2 + \sum_{x \in B_1} (deg(x))^2 + \sum_{x \in B_2} (deg(x))^2 \\ + \sum_{x \in B_3} (deg(x))^2 + \sum_{x \in B_4} (deg(x))^2 + \sum_{x \in B_5} (deg(x))^2 + \sum_{x \in B_6} (deg(x))^2 \\ = (|F_2| - 1)(|F_3| - 1)(|F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 + (|F_1| - 1) \\ (|F_3| - 1)(|F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \\ + (|F_1| - 1)(|F_2| - 1)(|F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 + (|F_3| - 1) \\ (|F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \\ + (|F_2| - 1)(|F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 + (|F_1| - 1) \\ (|F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \\ + (|J_2| - 1)(|J_3| - 1)(|J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 + (|J_1| - 1) \\ (|J_3| - 1)(|J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \\ + (|J_1| - 1)(|J_2| - 1)(|J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 + (|J_3| - 1) \\ (|J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \\ + (|J_2| - 1)(|J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 + (|J_1| - 1) \\ (|J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2.$$

3. The second Zagreb index [11, 14] is $M_2(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$

$$= \sum_{xy \in E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} deg(x)deg(y) \\ = \sum_{x \in A_1, y \in A_6} deg(x)deg(y) + \sum_{x \in A_2, y \in A_5} deg(x)deg(y) + \\ \sum_{x \in A_3, y \in A_4} deg(x)deg(y) \\ + \sum_{x \in A_4, y \in A_5} deg(x)deg(y) + \sum_{x \in A_4, y \in A_6} deg(x)deg(y) + \\ \sum_{x \in A_5, y \in A_6} deg(x)deg(y) \\ + \sum_{x \in B_1, y \in B_6} deg(x)deg(y) + \sum_{x \in B_2, y \in B_5} deg(x)deg(y) + \\ \sum_{x \in B_3, y \in B_4} deg(x)deg(y) \\ + \sum_{x \in B_4, y \in B_5} deg(x)deg(y) + \sum_{x \in B_4, y \in B_6} deg(x)deg(y) + \\ \sum_{x \in B_5, y \in B_6} deg(x)deg(y) \\ + \sum_{x \in A_1, y \in B_1} deg(x)deg(y) + \sum_{x \in A_1, y \in B_2} deg(x)deg(y) + \\ \sum_{x \in A_1, y \in B_3} deg(x)deg(y) \\ + \sum_{x \in A_1, y \in B_4} deg(x)deg(y) + \sum_{x \in A_1, y \in B_5} deg(x)deg(y) + \\ \sum_{x \in A_1, y \in B_6} deg(x)deg(y) \\ + \sum_{x \in A_2, y \in B_1} deg(x)deg(y) + \sum_{x \in A_2, y \in B_2} deg(x)deg(y) + \\ \sum_{x \in A_2, y \in B_3} deg(x)deg(y) \\ + \sum_{x \in A_2, y \in B_4} deg(x)deg(y) + \sum_{x \in A_2, y \in B_5} deg(x)deg(y) + \\ \sum_{x \in A_2, y \in B_6} deg(x)deg(y) \\ + \sum_{x \in A_3, y \in B_1} deg(x)deg(y) + \sum_{x \in A_3, y \in B_2} deg(x)deg(y) + \\ \sum_{x \in A_3, y \in B_3} deg(x)deg(y) \\ + \sum_{x \in A_3, y \in B_4} deg(x)deg(y) + \sum_{x \in A_3, y \in B_5} deg(x)deg(y) +$$

$$\begin{aligned}
& \sum_{x \in A_3, y \in B_6} \deg(x) \deg(y) \\
& + \sum_{x \in A_4, y \in B_1} \deg(x) \deg(y) + \sum_{x \in A_4, y \in B_2} \deg(x) \deg(y) + \\
& \sum_{x \in A_4, y \in B_3} \deg(x) \deg(y) \\
& + \sum_{x \in A_4, y \in B_4} \deg(x) \deg(y) + \sum_{x \in A_4, y \in B_5} \deg(x) \deg(y) + \\
& \sum_{x \in A_4, y \in B_6} \deg(x) \deg(y) \\
& + \sum_{x \in A_5, y \in B_1} \deg(x) \deg(y) + \sum_{x \in A_5, y \in B_2} \deg(x) \deg(y) + \\
& \sum_{x \in A_5, y \in B_3} \deg(x) \deg(y) \\
& + \sum_{x \in A_5, y \in B_4} \deg(x) \deg(y) + \sum_{x \in A_5, y \in B_5} \deg(x) \deg(y) + \\
& \sum_{x \in A_5, y \in B_6} \deg(x) \deg(y) \\
& + \sum_{x \in A_6, y \in B_1} \deg(x) \deg(y) + \sum_{x \in A_6, y \in B_2} \deg(x) \deg(y) + \\
& \sum_{x \in A_6, y \in B_3} \deg(x) \deg(y) \\
& + \sum_{x \in A_6, y \in B_4} \deg(x) \deg(y) + \sum_{x \in A_6, y \in B_5} \deg(x) \deg(y) + \\
& \sum_{x \in A_6, y \in B_6} \deg(x) \deg(y) \\
& = [(|F_1| - 1)(|F_2| \cdot |F_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|F_1| - 1)] \\
& + [(|F_2| - 1)(|F_1| \cdot |F_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|F_2| - 1)] \\
& + [(|F_3| - 1)(|F_1| \cdot |F_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|F_3| - 1)] \\
& + [(|F_1| \cdot |F_2| - 1)(|F_1| \cdot |F_3| - 1)][(|F_3| - 1)(|F_2| - 1)] \\
& + [(|F_1| \cdot |F_2| - 1)(|F_2| \cdot |F_3| - 1)][(|F_3| - 1)(|F_1| - 1)] \\
& + [(|F_1| \cdot |F_3| - 1)(|F_2| \cdot |F_3| - 1)][(|F_2| - 1)(|F_1| - 1)] \\
& + [(|J_1| - 1)(|J_2| \cdot |J_3| - 1)][(|J_2| - 1)(|J_3| - 1)(|J_1| - 1)] \\
& + [(|J_2| - 1)(|J_1| \cdot |J_3| - 1)][(|J_1| - 1)(|J_3| - 1)(|J_2| - 1)] \\
& + [(|J_3| - 1)(|J_1| \cdot |J_2| - 1)][(|J_1| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& + [(|J_1| \cdot |J_2| - 1)(|J_1| \cdot |J_3| - 1)][(|J_3| - 1)(|J_2| - 1)] \\
& + [(|J_1| \cdot |J_2| - 1)(|J_2| \cdot |J_3| - 1)][(|J_3| - 1)(|J_1| - 1)] \\
& + [(|J_1| \cdot |J_3| - 1)(|J_2| \cdot |J_3| - 1)][(|J_2| - 1)(|J_1| - 1)] \\
& + [(|F_1| - 1)(|J_1| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& + [(|F_1| - 1)(|J_2| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& + [(|F_1| - 1)(|J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& + [(|F_1| - 1)(|J_1| \cdot |J_2| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_3| - 1)] \\
& + [(|F_1| - 1)(|J_1| \cdot |J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_2| - 1)] \\
& + [(|F_1| - 1)(|J_2| \cdot |J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)] \\
& + [(|F_2| - 1)(|J_1| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& + [(|F_2| - 1)(|J_2| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& + [(|F_2| - 1)(|J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& + [(|F_2| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_3| - 1)] \\
& + [(|F_2| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_2| - 1)] \\
& + [(|F_2| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)] \\
& + [(|F_3| - 1)(|J_1| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& + [(|F_3| - 1)(|J_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& + [(|F_3| - 1)(|J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& + [(|F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_3| - 1)]
\end{aligned}$$

$$\begin{aligned}
& +[(|F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_2| - 1)] \\
& +[(|F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_1| - 1)][(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_2| - 1)][(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_3| - 1)][(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_1| \cdot |J_2| - 1)][(|F_3| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_1| \cdot |J_3| - 1)][(|F_3| - 1)(|J_2| - 1)] \\
& +[(|F_1| \cdot |F_2| - 1)(|J_2| \cdot |J_3| - 1)][(|F_3| - 1)(|J_1| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_1| - 1)][(|F_2| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_2| - 1)][(|F_2| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_3| - 1)][(|F_2| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_2| - 1)(|J_3| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_2| - 1)(|J_2| - 1)] \\
& +[(|F_1| \cdot |F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_2| - 1)(|J_1| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_1| - 1)][(|F_1| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_2| - 1)][(|F_1| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_3| - 1)][(|F_1| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|J_3| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|J_2| - 1)] \\
& +[(|F_2| \cdot |F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|J_1| - 1)].
\end{aligned}$$

4. The Forgotten topological index [5] is

$$\begin{aligned}
& F(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = \sum_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} (deg(x))^3 \\
& = \sum_{x \in A_1} (deg(x))^3 + \sum_{x \in A_2} (deg(x))^3 + \sum_{x \in A_3} (deg(x))^3 + \sum_{x \in A_4} (deg(x))^3 \\
& + \sum_{x \in A_5} (deg(x))^3 + \sum_{x \in A_6} (deg(x))^3 + \sum_{x \in B_1} (deg(x))^3 + \sum_{x \in B_2} (deg(x))^3 \\
& + \sum_{x \in B_3} (deg(x))^3 + \sum_{x \in B_4} (deg(x))^3 + \sum_{x \in B_5} (deg(x))^3 + \sum_{x \in B_6} (deg(x))^3 \\
& = (|F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_2| - 1)(|F_3| - 1) + (|F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_1| - 1)(|F_3| - 1) \\
& + (|F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_1| - 1)(|F_2| - 1) + (|F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_3| - 1) \\
& + (|F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_2| - 1) + (|F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^3(|F_1| - 1) \\
& + (|J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_2| - 1)(|J_3| - 1) + (|J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_1| - 1)(|J_3| - 1) \\
& + (|J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_1| - 1)(|J_2| - 1) + (|J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_3| - 1) \\
& + (|J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_2| - 1) + (|J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^3(|J_1| - 1).
\end{aligned}$$

5. The Narumi-Katayama index [13] is

$$\begin{aligned}
& NK(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = \prod_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} deg(x) \\
& = \prod_{x \in A_1} deg(x) \cdot \prod_{x \in A_2} deg(x) \cdot \prod_{x \in A_3} deg(x) \cdot \prod_{x \in A_4} deg(x) \cdot \prod_{x \in A_5} deg(x) \cdot \prod_{x \in A_6} deg(x)
\end{aligned}$$

$$\begin{aligned}
& \prod_{x \in B_1} \deg(x) \cdot \prod_{x \in B_2} \deg(x) \cdot \prod_{x \in B_3} \deg(x) \cdot \prod_{x \in B_4} \deg(x) \cdot \prod_{x \in B_5} \deg(x) \cdot \\
& \prod_{x \in B_6} \deg(x) \\
& = [(|F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_2| - 1)(|F_3| - 1)] \cdot [(|F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_1| - 1)(|F_3| - 1)] \cdot [(|F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_1| - 1)(|F_2| - 1)] \cdot [(|F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_3| - 1)] \cdot [(|F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_2| - 1)] \cdot [(|F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)(|F_1| - 1)] \\
& \cdot [(|J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_2| - 1)(|J_3| - 1)] \cdot [(|J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_1| - 1)(|J_3| - 1)] \cdot [(|J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_1| - 1)(|J_2| - 1)] \cdot [(|J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_3| - 1)] \cdot [(|J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_2| - 1)] \cdot [(|J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)(|J_1| - 1)] \\
& = (|F_1| - 1)^3 \cdot (|F_2| - 1)^3 \cdot (|F_3| - 1)^3 \cdot (|F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|) \cdot (|J_1| - 1)^3 \cdot (|J_2| - 1)^3 \cdot (|J_3| - 1)^3 \cdot (|J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|) \cdot (|J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|) \cdot (|J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|) \cdot (|J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|) \cdot (|J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|) \cdot (|J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|).
\end{aligned}$$

6. The first multiplicative Zagreb index [1, 18] is

$$\begin{aligned}
& \Pi_1(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) \\
& = \prod_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} (\deg(x))^2 \\
& = NK(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))^2 \\
& = (|F_1| - 1)^6 \cdot (|F_2| - 1)^6 \cdot (|F_3| - 1)^6 \cdot (|F_1| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \cdot (|F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \\
& \cdot (|F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \cdot (|F_1| \cdot |F_2| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \cdot (|F_1| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \\
& \cdot (|F_2| \cdot |F_3| - 1 + |V(\Gamma(J_1 \times J_2 \times J_3))|)^2 \cdot (|J_1| - 1)^6 \cdot (|J_2| - 1)^6 \cdot (|J_3| - 1)^6 \cdot (|J_1| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \\
& \cdot (|J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \cdot (|J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \cdot (|J_1| \cdot |J_2| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \\
& \cdot (|J_1| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2 \cdot (|J_2| \cdot |J_3| - 1 + |V(\Gamma(F_1 \times F_2 \times F_3))|)^2.
\end{aligned}$$

7. The second multiplicative Zagreb index [1, 18] is

$$\begin{aligned}
& \Pi_2(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) \\
& = \prod_{xy \in E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} \deg(x)\deg(y) \\
& = \prod_{x \in A_1, y \in A_6} \deg(x)\deg(y) \cdot \prod_{x \in A_2, y \in A_5} \deg(x)\deg(y) \cdot \prod_{x \in A_3, y \in A_4} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_4, y \in A_5} \deg(x)\deg(y) \cdot \prod_{x \in A_4, y \in A_6} \deg(x)\deg(y) \cdot \prod_{x \in A_5, y \in A_6} \deg(x)\deg(y) \\
& \cdot \prod_{x \in B_1, y \in B_6} \deg(x)\deg(y) \cdot \prod_{x \in B_2, y \in B_5} \deg(x)\deg(y) \cdot \prod_{x \in B_3, y \in B_4} \deg(x)\deg(y) \\
& \cdot \prod_{x \in B_4, y \in B_5} \deg(x)\deg(y) \cdot \prod_{x \in B_4, y \in B_6} \deg(x)\deg(y) \cdot \prod_{x \in B_5, y \in B_6} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_1, y \in B_1} \deg(x)\deg(y) \cdot \prod_{x \in A_1, y \in B_2} \deg(x)\deg(y) \cdot \prod_{x \in A_1, y \in B_3} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_1, y \in B_4} \deg(x)\deg(y) \cdot \prod_{x \in A_1, y \in B_5} \deg(x)\deg(y) \cdot \prod_{x \in A_1, y \in B_6} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_2, y \in B_1} \deg(x)\deg(y) \cdot \prod_{x \in A_2, y \in B_2} \deg(x)\deg(y) \cdot \prod_{x \in A_2, y \in B_3} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_2, y \in B_4} \deg(x)\deg(y) \cdot \prod_{x \in A_2, y \in B_5} \deg(x)\deg(y) \cdot \prod_{x \in A_2, y \in B_6} \deg(x)\deg(y) \\
& \cdot \prod_{x \in A_3, y \in B_1} \deg(x)\deg(y) \cdot \prod_{x \in A_3, y \in B_2} \deg(x)\deg(y) \cdot \prod_{x \in A_3, y \in B_3} \deg(x)\deg(y)
\end{aligned}$$

$$\begin{aligned}
& \cdot \prod_{x \in A_3, y \in B_4} \deg(x) \deg(y) \cdot \prod_{x \in A_3, y \in B_5} \deg(x) \deg(y) \cdot \prod_{x \in A_3, y \in B_6} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_4, y \in B_1} \deg(x) \deg(y) \cdot \prod_{x \in A_4, y \in B_2} \deg(x) \deg(y) \cdot \prod_{x \in A_4, y \in B_3} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_4, y \in B_4} \deg(x) \deg(y) \cdot \prod_{x \in A_4, y \in B_5} \deg(x) \deg(y) \cdot \prod_{x \in A_4, y \in B_6} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_5, y \in B_1} \deg(x) \deg(y) \cdot \prod_{x \in A_5, y \in B_2} \deg(x) \deg(y) \cdot \prod_{x \in A_5, y \in B_3} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_5, y \in B_4} \deg(x) \deg(y) \cdot \prod_{x \in A_5, y \in B_5} \deg(x) \deg(y) \cdot \prod_{x \in A_5, y \in B_6} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_6, y \in B_1} \deg(x) \deg(y) \cdot \prod_{x \in A_6, y \in B_2} \deg(x) \deg(y) \cdot \prod_{x \in A_6, y \in B_3} \deg(x) \deg(y) \\
& \cdot \prod_{x \in A_6, y \in B_4} \deg(x) \deg(y) \cdot \prod_{x \in A_6, y \in B_5} \deg(x) \deg(y) \cdot \prod_{x \in A_6, y \in B_6} \deg(x) \deg(y) \\
& = [(|F_1| - 1)(|F_2| \cdot |F_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|F_1| - 1)] \\
& \cdot [(|F_2| - 1)(|F_1| \cdot |F_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|F_2| - 1)] \\
& \cdot [(|F_3| - 1)(|F_1| \cdot |F_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|F_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|F_1| \cdot |F_3| - 1)][(|F_3| - 1)(|F_2| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|F_2| \cdot |F_3| - 1)][(|F_3| - 1)(|F_1| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|F_2| \cdot |F_3| - 1)][(|F_2| - 1)(|F_1| - 1)] \\
& \cdot [(|J_1| - 1)(|J_2| \cdot |J_3| - 1)][(|J_2| - 1)(|J_3| - 1)(|J_1| - 1)] \\
& \cdot [(|J_2| - 1)(|J_1| \cdot |J_3| - 1)][(|J_1| - 1)(|J_3| - 1)(|J_2| - 1)] \\
& \cdot [(|J_3| - 1)(|J_1| \cdot |J_2| - 1)][(|J_1| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|J_1| \cdot |J_2| - 1)(|J_1| \cdot |J_3| - 1)][(|J_3| - 1)(|J_2| - 1)] \\
& \cdot [(|J_1| \cdot |J_2| - 1)(|J_2| \cdot |J_3| - 1)][(|J_3| - 1)(|J_1| - 1)] \\
& \cdot [(|J_1| \cdot |J_3| - 1)(|J_2| \cdot |J_3| - 1)][(|J_2| - 1)(|J_1| - 1)] \\
& \cdot [(|F_1| - 1)(|J_1| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| - 1)(|J_2| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| - 1)(|J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| - 1)(|J_1| \cdot |J_2| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| - 1)(|J_1| \cdot |J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| - 1)(|J_2| \cdot |J_3| - 1)][(|F_2| - 1)(|F_3| - 1)(|J_1| - 1)] \\
& \cdot [(|F_2| - 1)(|J_1| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| - 1)(|J_2| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| - 1)(|J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_2| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_2| - 1)] \\
& \cdot [(|F_2| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|F_3| - 1)(|J_1| - 1)] \\
& \cdot [(|F_3| - 1)(|J_1| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_3| - 1)(|J_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_3| - 1)(|J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_2| - 1)] \\
& \cdot [(|F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|F_2| - 1)(|J_1| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_1| - 1)][(|F_3| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_2| - 1)][(|F_3| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_3| - 1)][(|F_3| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_1| \cdot |J_2| - 1)][(|F_3| - 1)(|J_3| - 1)]
\end{aligned}$$

$$\begin{aligned}
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_1| \cdot |J_3| - 1)][(|F_3| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| \cdot |F_2| - 1)(|J_2| \cdot |J_3| - 1)][(|F_3| - 1)(|J_1| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_1| - 1)][(|F_2| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_2| - 1)][(|F_2| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_3| - 1)][(|F_2| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_2| - 1)(|J_2| - 1)] \\
& \cdot [(|F_1| \cdot |F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_2| - 1)(|J_1| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_1| - 1)][(|F_1| - 1)(|J_2| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_2| - 1)][(|F_1| - 1)(|J_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_3| - 1)][(|F_1| - 1)(|J_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_1| \cdot |J_2| - 1)][(|F_1| - 1)(|J_3| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_1| \cdot |J_3| - 1)][(|F_1| - 1)(|J_2| - 1)] \\
& \cdot [(|F_2| \cdot |F_3| - 1)(|J_2| \cdot |J_3| - 1)][(|F_1| - 1)(|J_1| - 1)] \\
& = (|F_1| - 1)^{30} \cdot (|F_2| - 1)^{30} \cdot (|F_3| - 1)^{30} \cdot (|F_1||F_2| - 1)^9 \cdot (|F_1||F_3| - 1)^9 \cdot (|F_2||F_3| - 1)^9 \\
& \cdot (|J_1| - 1)^{30} \cdot (|J_2| - 1)^{30} \cdot (|J_3| - 1)^{30} \cdot (|J_1||J_2| - 1)^9 \cdot (|J_1||J_3| - 1)^9 \cdot (|J_2||J_3| - 1)^9.
\end{aligned}$$

3 Eccentricity based topological indices

Example 3.1. By Example 2.1, (1), the diameter of the join graph

$\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is 2 and for

$x, y \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$ if

$xy \notin E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))$, then $d(x, y) = 2$. Therefore, the eccentricity $e(x)$ of each vertex x in the join graph

$\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is 2.

1. The total eccentricity [3], [4] of $\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)$ is

$$\begin{aligned}
& \xi(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = \sum_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} e(x) \\
& = 2[|V(\Gamma(F_1 \times F_2 \times F_3))| + |V(\Gamma(J_1 \times J_2 \times J_3))|].
\end{aligned}$$

2. The first Zagreb eccentricity index [1] is

$$\begin{aligned}
& E_1(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = \sum_{x \in V(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} (e(x))^2 \\
& = 4[|V(\Gamma(F_1 \times F_2 \times F_3))| + |V(\Gamma(J_1 \times J_2 \times J_3))|].
\end{aligned}$$

3. The second Zagreb eccentricity index [1] is

$$\begin{aligned}
& E_2(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3)) = \sum_{xy \in E(\Gamma(F_1 \times F_2 \times F_3) + \Gamma(J_1 \times J_2 \times J_3))} e(x)e(y) \\
& = \sum_{x \in A_1, y \in A_6} e(x)e(y) + \sum_{x \in A_2, y \in A_5} e(x)e(y) + \sum_{x \in A_3, y \in A_4} e(x)e(y) \\
& + \sum_{x \in A_4, y \in A_5} e(x)e(y) + \sum_{x \in A_4, y \in A_6} e(x)e(y) + \sum_{x \in A_5, y \in A_6} e(x)e(y) \\
& + \sum_{x \in B_1, y \in B_6} e(x)e(y) + \sum_{x \in B_2, y \in B_5} e(x)e(y) + \sum_{x \in B_3, y \in B_4} e(x)e(y) \\
& + \sum_{x \in B_4, y \in B_5} e(x)e(y) + \sum_{x \in B_4, y \in B_6} e(x)e(y) + \sum_{x \in B_5, y \in B_6} e(x)e(y) \\
& + \sum_{x \in A_1, y \in B_1} e(x)e(y) + \sum_{x \in A_1, y \in B_2} e(x)e(y) + \sum_{x \in A_1, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_1, y \in B_4} e(x)e(y) + \sum_{x \in A_1, y \in B_5} e(x)e(y) + \sum_{x \in A_1, y \in B_6} e(x)e(y) \\
& + \sum_{x \in A_2, y \in B_1} e(x)e(y) + \sum_{x \in A_2, y \in B_2} e(x)e(y) + \sum_{x \in A_2, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_2, y \in B_4} e(x)e(y) + \sum_{x \in A_2, y \in B_5} e(x)e(y) + \sum_{x \in A_2, y \in B_6} e(x)e(y)
\end{aligned}$$



$$\begin{aligned}
& + \sum_{x \in A_3, y \in B_1} e(x)e(y) + \sum_{x \in A_3, y \in B_2} e(x)e(y) + \sum_{x \in A_3, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_3, y \in B_4} e(x)e(y) + \sum_{x \in A_3, y \in B_5} e(x)e(y) + \sum_{x \in A_3, y \in B_6} e(x)e(y) \\
& + \sum_{x \in A_4, y \in B_1} e(x)e(y) + \sum_{x \in A_4, y \in B_2} e(x)e(y) + \sum_{x \in A_4, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_4, y \in B_4} e(x)e(y) + \sum_{x \in A_4, y \in B_5} e(x)e(y) + \sum_{x \in A_4, y \in B_6} e(x)e(y) \\
& + \sum_{x \in A_5, y \in B_1} e(x)e(y) + \sum_{x \in A_5, y \in B_2} e(x)e(y) + \sum_{x \in A_5, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_5, y \in B_4} e(x)e(y) + \sum_{x \in A_5, y \in B_5} e(x)e(y) + \sum_{x \in A_5, y \in B_6} e(x)e(y) \\
& + \sum_{x \in A_6, y \in B_1} e(x)e(y) + \sum_{x \in A_6, y \in B_2} e(x)e(y) + \sum_{x \in A_6, y \in B_3} e(x)e(y) \\
& + \sum_{x \in A_6, y \in B_4} e(x)e(y) + \sum_{x \in A_6, y \in B_5} e(x)e(y) + \sum_{x \in A_6, y \in B_6} e(x)e(y) \\
& = [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|F_1| - 1)] + [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|F_2| - 1)] + \\
& [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|F_3| - 1)] + [2(|F_3| - 1)] \cdot [2(|F_2| - 1)] + [2(|F_3| - 1)] \cdot \\
& [2(|F_1| - 1)] + [2(|F_2| - 1)] \cdot [2(|F_1| - 1)] \\
& + [2(|J_2| - 1) \cdot (|J_3| - 1)] \cdot [2(|J_1| - 1)] + [2(|J_1| - 1) \cdot (|J_3| - 1)] \cdot [2(|J_2| - 1)] + \\
& [2(|J_1| - 1) \cdot (|J_2| - 1)] \cdot [2(|J_3| - 1)] + [2(|J_3| - 1)] \cdot [2(|J_2| - 1)] + [2(|J_3| - 1)] \cdot \\
& [2(|J_1| - 1)] + [2(|J_2| - 1)] \cdot [2(|J_1| - 1)] \\
& + \\
& [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_2| - 1)(|J_3| - 1)] + [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)(|J_3| - 1)] + \\
& [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)(|J_2| - 1)] + [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot \\
& [2(|J_3| - 1)] + [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_2| - 1)] + [2(|F_2| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)] \\
& + \\
& [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_2| - 1)(|J_3| - 1)] + [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)(|J_3| - 1)] + \\
& [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)(|J_2| - 1)] + [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot \\
& [2(|J_3| - 1)] + [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_2| - 1)] + [2(|F_1| - 1) \cdot (|F_3| - 1)] \cdot [2(|J_1| - 1)] \\
& + \\
& [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|J_2| - 1)(|J_3| - 1)] + [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|J_1| - 1)(|J_3| - 1)] + \\
& [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|J_1| - 1)(|J_2| - 1)] + [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|J_3| - 1)] + [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot \\
& [2(|J_2| - 1)] + [2(|F_1| - 1) \cdot (|F_2| - 1)] \cdot [2(|J_1| - 1)] \\
& + [2(|F_2| - 1)] \cdot [2(|J_2| - 1)(|J_3| - 1)] + [2(|F_2| - 1)] \cdot [2(|J_1| - 1)(|J_3| - 1)] + \\
& [2(|F_2| - 1)] \cdot [2(|J_1| - 1)(|J_2| - 1)] + [2(|F_2| - 1)] \cdot [2(|J_3| - 1)] + [2(|F_2| - 1)] \cdot \\
& [2(|J_2| - 1)] + [2(|F_2| - 1)] \cdot [2(|J_1| - 1)] \\
& + [2(|F_1| - 1)] \cdot [2(|J_2| - 1)(|J_3| - 1)] + [2(|F_1| - 1)] \cdot [2(|J_1| - 1)(|J_3| - 1)] + \\
& [2(|F_1| - 1)] \cdot [2(|J_1| - 1)(|J_2| - 1)] + [2(|F_1| - 1)] \cdot [2(|J_3| - 1)] + [2(|F_1| - 1)] \cdot \\
& [2(|J_2| - 1)] + [2(|F_1| - 1)] \cdot [2(|J_1| - 1)]. \\
\end{aligned}$$

4. **The eccentricity connectivity [1] is** $\xi^c(\Gamma(R)) = \sum_{x \in V(\Gamma(R))} e(x) \deg(x)$
 $= 6(|F_1| - 1) \cdot (|F_2| - 1) \cdot (|F_3| - 1) + 6(|J_1| - 1) \cdot (|J_2| - 1) \cdot (|J_3| - 1) + 2(|F_1| \cdot |F_2| - 1)[(|F_3| - 1)] + 2(|F_1| \cdot |F_3| - 1)[(|F_2| - 1)] + 2(|F_2| \cdot |F_3| - 1)[(|F_1| - 1)] + 2(|J_1| \cdot |J_2| - 1)[(|J_3| - 1)] + 2(|J_1| \cdot |J_3| - 1)[(|J_2| - 1)] + 2(|J_2| \cdot |J_3| - 1)[(|J_1| - 1)].$

4 Conclusion

We have calculated Wiener index, degree based topological indices and eccentricity based topological indices of the join graph of zero divisor graphs of direct product of three finite fields in terms of the order of fields.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Declaration of Generative AI and AI-assisted technologies in the writing process

The authors declare that they have not used generative AI and AI-assisted technologies in the writing process.

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